## THE GROWTII AND DECAY OF SHIP wavES

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The spatial problem of the growth and decay of surface waves, which arise as a result of the rectilinear motion of a pressure system with constant velocity $c$ along a free surface, is investigated. Analogons problems are examined in the case of steady motions in $[1-4]$.

1. Starting with the moment of time $t=0$, let pressure of the form $p=p_{0} a(x, y)$ be applied to the horizontal free surface of a fluid occupying the half-plane $z<0$ and flowing in the positive direction of the $x$-axis with the velocity $c$. Assuming the motion of the fluid to be irrotational, we write the velocity potential in the form

$$
\Phi(x, y, z, t)=c x+\varphi(x, y, z, t)
$$

The potential of the perturbed motion $\varphi(x, y, z, t)$ must satisfy the following conditions [2]:

$$
\begin{gather*}
\Delta \varphi=0, \quad z<0  \tag{1.1}\\
\varphi_{t t}+g \varphi_{z}+2 c \varphi_{x t}+c^{2} \varphi_{x x}=-c \rho^{-1} p_{0} a_{x}, \quad z=0  \tag{1.2}\\
\varphi(x, y, z, 0)=0, \quad \varphi_{t}+c \varphi_{x}=-p_{0} \rho^{-1} a, \quad z=0, \quad t=0 \tag{1.3}
\end{gather*}
$$

In addition, the elevation $\zeta(x, y, t)$ of the free surface of the fluid is given by the formula

$$
\begin{equation*}
\zeta=-g^{-1}\left[\varphi_{i}+c \varphi_{x}+p_{0} \rho^{-1} a\right]_{z=0} \tag{1.4}
\end{equation*}
$$

Conditions (1.3) express the fact that at the initial moment of time there is no perturbed motion and the free surface is horizontal. Applying Fourier transforms with respect to the variables $x$ and $y$ to (1.1) to (1.4), we obtain

$$
\begin{gather*}
\Phi_{z z}-\left(m^{2}+n^{2}\right) \Phi=0, \quad z<0  \tag{1.5}\\
\Phi_{t t}+g \Phi_{z}+2 \operatorname{cim} \Phi_{t}-m^{2} c^{2} \Phi=-c P^{-1} p_{0} \quad i m A, \quad z=0  \tag{1.6}\\
\Phi(m, n, z, 0)=0, \quad \Phi_{i}+i m c \Phi=-p_{0} \rho^{-1} A_{1} \quad z=0, \quad t=0  \tag{1.7}\\
Z=-g^{-1}\left(\Phi_{t}+\operatorname{cim} \Phi+p_{0} p^{-1} A\right)_{z=0} \tag{1.8}
\end{gather*}
$$

where $\Phi, A, Z$ are the Fourier transforms of the functions $\varphi, a, \zeta$. The solution of equation (1.5) which satisfies the condition $\Phi \rightarrow 0$ as $z \rightarrow-\infty$ has the form

$$
\begin{equation*}
\Phi=B(m, n, t) e^{z \sqrt{m^{z}+n^{2}}} \tag{1.9}
\end{equation*}
$$

Satisfying conditions (1.6) to (1.7), we obtain

$$
\begin{gathered}
B_{t t}+2 \operatorname{cim} B_{t}+\left(g \sqrt{m^{2}+n^{2}}-m^{2} c^{2}\right) B=-\operatorname{cimp}^{-1} p_{0} A \\
B(m, n, 0)=0, \quad B_{t}(m, n, 0)=-p_{0} P^{-1} A
\end{gathered}
$$

Hence

$$
\begin{gathered}
B(m, n, t)=B_{0}+B_{1} e^{i k_{1} t}+B_{2} e^{i k_{2} l} \\
B_{0}=\frac{c i m_{0} p_{0} A}{\rho\left[c^{2}-\alpha^{2}\right]}, \quad B_{1,2}=-\frac{i p_{0} A}{2 \rho[c m \mp \alpha]}, \quad k_{1,2}=-c m \pm \alpha, \quad \alpha=\sqrt[4]{g^{2}\left(m^{2}+n^{2}\right)}
\end{gathered}
$$

Applying inverse Fourier transforms, we find from formulas (1.8) and (1.9)

$$
\begin{gather*}
\zeta=\frac{p_{0}}{4 \pi \rho g} \lim _{z \rightarrow-0}\left[\int_{-\infty}^{\infty} f(m, n, t) e^{i(m x+n y)+z \sqrt{m^{2}+n^{2}} d m d n}\right]  \tag{1.11}\\
f(m, n, t)=A(m, n)\left[\frac{2 c^{2} m^{2}}{c^{2} m^{2}-\alpha^{2}}-\frac{\alpha}{c m-\alpha} e^{i k_{1} t}+\frac{\alpha}{c m+\alpha} e^{i k_{2} t}\right] \\
\varphi=\frac{1}{2 \pi} \iint_{-\infty}^{\infty} B(m, n, t) e^{z \sqrt{m^{2}+n^{2}}} d m d n \tag{1.12}
\end{gather*}
$$

2. Formulas (1.11) and (1.12) give an exact solution to the posed problem for an arbitrary function $a(x, y)$. We shall carry out an investigation of these formulas for a function $a(x, y)$ which is equal to unity in the square $|x|<b,|y|<b$ and is equal to zero outside of this square. In this case

$$
\begin{equation*}
A(m, n)=\frac{2 \sin m b \sin n b}{\pi m n} \tag{2.1}
\end{equation*}
$$

We shall assume further that $b$ is small but that $p_{0}$ is so large that
the total pressure force $P=p_{0} b^{2}$ has a finite value. Taking (2.1) into consideration we write expressions (1.11) and (1.12) in the following form:

$$
\begin{gather*}
\varphi=-\frac{p_{0}}{2 \pi \rho} \operatorname{Im}\left[\int_{0}^{\infty} \frac{A(m, n)}{(c m-\alpha)}\left(1-e^{i k_{i} t}\right) e^{i(m x+n \nu)+z \sqrt{m^{2}+n^{2}}} d m d n\right]  \tag{2.2}\\
\zeta=\frac{p_{0}}{2 \pi \rho g} \lim _{z \rightarrow-0}\left[\operatorname{Re} \int_{-\infty}^{\infty} \frac{A(m, n)}{c m-\alpha}\left(c m-\alpha e^{i k_{1} t}\right) e^{i(m x+n y)+z \sqrt{m^{2}+n^{2}}} d m d n\right] \tag{2.3}
\end{gather*}
$$

We shall introduce the notations

$$
\begin{gathered}
m=x r \cos \theta, \quad n=x r \sin \theta, \quad x=R \cos \psi, \quad y=R \sin \psi \\
x=g c^{-2}, \quad t_{1}=\tan c^{-1}, \quad z_{1}=x z, \quad b_{1}=x b, \quad R_{1}=x R
\end{gathered}
$$

Expression (2.3) takes the form

$$
\begin{equation*}
\stackrel{F}{5} \frac{p_{0}}{\pi^{2} \rho g} \lim _{z \rightarrow 0} \operatorname{Re}\left[\int_{0}^{\infty} I(r) e^{z r} d r\right], \quad I(r)=\int_{-1 / 2 \pi}^{z / 2 \pi} \xi(\theta) e^{i r R \cos (\theta-\psi)} d \theta \tag{2.4}
\end{equation*}
$$

where

$$
\begin{gather*}
\xi(\theta)=f_{1}(\theta)\left[\sqrt{r} \cos \theta-e^{-i \sqrt{r}(\sqrt{r} \cos \theta-1) t}\right]  \tag{2.5}\\
f_{1}(\theta)=\frac{\sin (b r \cos \theta) \sin (b r \sin \theta)}{r(\sqrt{r} \cos \theta-1) \sin 2 \theta}
\end{gather*}
$$

Here the index of unity on $R, z$ and $b$ has been omitted for simplicity in writing. Since the function $\xi(\theta)$ does not have singularities along the path of integration $-1 / 2 \pi \leqslant \theta \leqslant 3 / 2 \pi$ for any $r$, including also $r=0$ since $\zeta(\theta) \rightarrow 0$ as $r \rightarrow 0$, the original path of integration in formula (2.5) can then be replaced by the path $L$ which runs along the real axis with a bypass around the point $\theta_{1}$ by means of a small semicircle in the lower half-plane and around the point $\theta_{2}$ in the upper halfplane, where

$$
-1 / 2 \pi<\theta_{1}<0, \quad 0<\theta_{2}<1 / 2 \pi, \quad \cos \theta_{1}=\cos \theta_{2}=r^{-1 / 2}
$$

Along the chosen contour $L$ we have $\operatorname{Re}[-$ ir $\cos \theta] \leqslant 0$. The integral (2.5) can now be written as

$$
\begin{gather*}
I=I_{1}-I_{2}  \tag{2.6}\\
I_{1}=\int_{(L)} f_{1}(\theta) \sqrt{r} e^{i r R \cos (\theta-\psi)} \cos \theta d \theta, \quad I_{2}=\int_{(L)} f_{1}(\theta) e^{i \operatorname{Rr} M(\theta)} d \theta  \tag{2.7}\\
M(\theta)=\cos (\theta-\psi)-v\left[\cos \theta-r^{-1 / 2}\right], \quad v=t R^{-1} \tag{2.8}
\end{gather*}
$$

In an analogous manner expression (2.2) can be written in the following form:

$$
\begin{gather*}
\varphi=-\frac{c p_{0}}{\pi^{2} \rho g} \operatorname{Im}\left[\int_{0}^{\infty}\left(K_{1}(r)-K_{2}(r)\right) e^{z r} \frac{1}{\sqrt{r}} d r\right]  \tag{2.9}\\
K_{1}=\int_{(L)} f_{1}(\theta) e^{i r R \cos (\theta-\psi)} d \theta, \quad K_{2}=\int_{(L)} f_{1}(\theta) e^{i R r M(\theta)} d \theta \tag{2.10}
\end{gather*}
$$

Evaluating the integrals (2.7) for large values of $R$ by the method of stationary phase $[1,2]$ for $r>1$, we find

$$
\begin{array}{cc}
I_{1}=a_{1}+a_{2}+a_{3}, & I_{2}=b_{1}+b_{2}+b_{3} \\
a_{1}=-2 \pi i\left[\operatorname{res} \psi_{1}(\theta)\right]_{\theta_{2}}, & \cos \psi>0, \quad \sqrt{\bar{r}}>\sec \psi
\end{array}
$$

$$
a_{2}=2 \pi i\left[\operatorname{res} \psi_{1}(\theta)\right]_{\theta_{2}}, \quad \cos \psi>0, \quad r>1 ; \quad \cos \psi<0, \quad \sqrt{r}<-\sec \psi
$$

$$
a_{3}=R^{-1 / 3} d_{1}(r) e^{i R q_{1}(r)}
$$

$$
b_{1}=2 \pi i\left[\operatorname{res} \psi_{2}(\theta)\right]_{\theta_{1}}, \quad 0<\psi<\pi, \quad v<v_{1}, \quad r>1
$$

$b_{2}=-2 \pi i \operatorname{res}\left[\psi_{2}(\theta)\right]_{\theta_{2}}, \quad \cos \psi>v>\cos \psi-(r-1)^{-1 / 2} \sin \psi, \quad r>1$

$$
\begin{gathered}
b_{3}=R^{-1 / 2} d_{2}(r) e^{i R q_{1}(r)} \\
v_{1}=(\sqrt{r-1} \cos \psi+\sin \psi) / \sqrt{r-1}
\end{gathered}
$$

Here the integrands of the integrals (2.7) are denoted by $\Psi_{1}(\theta)$ and $\Psi_{2}(\theta) ; d_{1}(r), d_{2}(r)$ denote functions which do not have singularities; and the functions $q_{1}(r), q_{2}(r)$ are real for $r>0$.

From formulas (2.11), (2.6) and (2.4) we find

$$
\begin{equation*}
\zeta=\frac{p_{0}}{\pi^{2} \mathrm{pg}} \lim _{z \rightarrow 0} \operatorname{Re}\left[\sum_{k=3}^{11} I_{k}\right] \tag{2.12}
\end{equation*}
$$

Here the $I_{k}$ are determined by the formulas

$$
\begin{equation*}
I_{3}=\pi i \int_{i}^{\infty} \xi_{1}(r) e^{[i R \sqrt{r}(\cos \psi-\sqrt{r-1} \sin \psi)]} d r\binom{\cos \psi>0}{v>v_{1}} \tag{2.13}
\end{equation*}
$$

$$
\begin{gather*}
I_{4}=\int_{0}^{1} \int_{-1 / 2 \pi}^{z / 2 \pi} f_{1}(\theta) \sqrt{r} \cos \theta e^{i r R \cos (\theta-\psi)+z r} d \theta d r, I_{5}=\int_{0}^{1} \int_{-1 / 2 \pi}^{s / 2 \pi} f_{1}(\theta) e^{i R r M(\theta)+z r} d \theta d r(2.14) \\
I_{6}=\int_{i}^{\Psi} \int_{1}^{\Psi} \xi_{1}(r) e^{i R \sqrt{r}(\cos \psi-\sqrt{r-1} \sin \psi)} d r \quad\binom{\cos \psi<0}{v>v_{1}} \quad\left(\Psi=\frac{1}{\cos ^{2} \psi}\right) \\
I_{7}=-\pi i \int_{\Psi}^{\infty} \xi_{1}(r) e^{i R \sqrt{r}(\cos \psi-\sqrt{r-1} \sin \psi)} d r \quad\binom{\cos \psi<0}{v<v_{1}} \tag{2.15}
\end{gather*}
$$

$$
\begin{gathered}
I_{8}=\pi i \int_{\underset{\Psi}{*}}^{\infty} \xi_{1}(r) e^{i R \sqrt{r}(\cos \psi+\sqrt{r-1} \sin \psi)} d r \quad\binom{\cos \psi>0}{v>0} \\
I_{8}=-\pi i \int_{1}^{\infty} \xi_{1}(r) e^{i R \sqrt{r}(\cos \psi+\sqrt{r-1} \sin \psi)} d r \quad\left(\cos \psi<v<\cos \psi-\frac{\sin \psi}{\sqrt{r-1}}\right) \\
I_{10,11}=\frac{1}{\sqrt{R}} \int_{1}^{\infty} d_{1,2}(r) e^{i R q_{1,2}(r)+z r} d r,
\end{gathered}
$$

In formulas (2.13) to (2.15)

$$
\xi_{1}(r)=\frac{\sin b \sqrt{r} \sin b \sqrt{r(r-1)}}{r-1} e^{z r}
$$

Carrying out evaluations of the integrals $I_{k}(k=4, \ldots, 11)$ for large values of $R$, and taking into consideration that $d_{1}(r), d_{2}(r)$ and the integrands in $I_{4}$ and $I_{5}$ according to (2.14) do not have singularities in the region of integration [5], and that the $I_{k}(k=6,7,8,9)$ do not have stationary points on the path of integration, we find that each of these integrals is of order not lower than $R^{-1}$ and that therefore

$$
I_{4}+I_{5}+\ldots+I_{11}=0\left(R^{-1}\right)
$$

We shall pass on to the investigation of the integral $I_{3}$; we represent it in the following form:

$$
\begin{equation*}
I_{\mathrm{z}}=2 \pi i \int_{0}^{\infty} \frac{\cosh r \sin (b \cosh r) \sin (b \cosh r \sinh r)}{\sinh r} e^{i R N(r)+z \cosh ^{2} r} d r \tag{2.16}
\end{equation*}
$$

Here

$$
N(r)=\cosh r(\cos \psi-\sinh r \sin \psi), \quad \cos \psi>0, \quad v>v_{1}=\frac{\sinh r \cos \psi+\sin \psi}{\sinh r}
$$

The equation $N^{\prime}(r)=0$ has the roots

$$
\sinh r_{1,2}=\frac{\cos \psi \pm \sqrt{9 \cos ^{2} \psi-8}}{4 \sin \psi}
$$

Since the stationary points of the integrand of (2.16) occur only for $0<\Psi<19^{\circ} 28^{\prime}$, we obtain for $I_{3}$ the asymptotic expression for large values of $R$

$$
I_{3}= \begin{cases}2 \pi i R^{-1 / 4} \Sigma A_{k} \exp \left\{i R \left[N\left(r_{k}\right)+(-1)^{\left.\left.k_{1} / \ell \pi\right]+z \cosh ^{2} r_{k}\right\}}\right.\right. & \left(0<\psi<19^{\circ} 28^{\prime}\right)  \tag{2.17}\\ 2 \pi i R^{-1 / 3} A_{3} \exp \left[i R N\left(r_{3}\right)+2 \cosh ^{2} r_{3}\right] & \left(\psi=19^{\circ} 28^{\prime}\right) \\ O\left(R^{-1}\right) & \left(19^{\circ} 28^{\prime}<\psi<\pi\right)\end{cases}
$$

$$
\begin{aligned}
& A_{k}=\left[\frac{\sqrt{\cosh r} \sqrt{2 \pi} \sin (b \cosh r) \sin (b \cosh r \sinh r)}{\sinh r \sqrt[4]{9 \cos ^{2} \psi-8}}\right]_{r_{k}} \quad(k=1,2) \\
& A_{3}=3^{5 / 142^{1 / 4} \Gamma(1 / 3) \sin (1 / 2 \sqrt{3} b) \sin (1 / 2 \sqrt{2} b), \quad \sinh r_{3}=1 / 2 \sqrt{2}}
\end{aligned}
$$

From formulas (2.12), (2.15) and (2.17) we find the expressions for $\zeta$ for large $k R$

$$
\begin{gather*}
\zeta= \begin{cases}\eta_{1}+\eta_{2} & \left(0<\psi<19^{\circ} 28^{\prime}\right) \\
O\left[(x R)^{-1}\right] & \left(19^{\circ} 28^{\prime}<\psi \leqslant \pi\right)\end{cases}  \tag{2.18}\\
\eta_{1,2}= \begin{cases}B_{1,2}(x R)^{-1 / 2} \sin \left[N\left(r_{1,2}\right) x R \mp{ }^{1 / 4 \pi]}\right. & \left(R<c t u_{1,2}(\psi)\right) \\
O\left[(x R)^{-1}\right] & \left(R>c t u_{1,2}(\psi)\right)\end{cases}
\end{gather*}
$$

For $\Psi=19^{\circ} 28^{\prime}$ we have

$$
\zeta= \begin{cases}B_{3}(x R)^{-1 / 3} \sin (1 / 2 \sqrt{3} x R) & (R<1 / 2 \sqrt{2} c t)  \tag{2.19}\\ O\left[(x R)^{-2 / 3}\right] & (R>1 / 2 \sqrt{2} c t)\end{cases}
$$

$B_{k}=-\frac{2 p_{0}}{\pi \rho g} A_{k} \quad(k=1,2,3), \quad u_{1,2}(\psi)=\frac{\cos \psi \pm \sqrt{9 \cos ^{2} \psi-8}}{4 \sin ^{2} \psi+\left(\cos \psi \pm \sqrt{9 \cos ^{2} \psi-8}\right) \cos \psi}$
We set $\Psi=0$ in the integrals (2,7) and, finding their asymptotic value for large $k R$, we have the following expression for $\zeta$ for $\Psi=0$ :

$$
\zeta=\left\{\begin{array}{ll}
B_{4}(x R)^{-1 / 2} \sin (x R+1 / 4 \pi) & (R<c t)  \tag{2.20}\\
O\left[(x R)^{-1}\right] & (R>c t)
\end{array} \quad\left(B_{4}=-\frac{2 \sqrt{2} p_{0} b \sin b}{\sqrt{\pi} \rho g}\right)\right.
$$

For a pressure which is concentrated at the origin of the coordinate system, i.e. in the case $b \rightarrow 0, p_{0} \rightarrow \infty$, $b^{2} p_{0}=P=$ const, formulas (2.18) to (2.20) remain valid themselves but the expressions for $B_{k}$ in this case take the following form:

$$
\begin{gather*}
B_{1,2}=-\left[\frac{2 \sqrt{2} x^{2} P(\cosh r)^{3 / 2}}{\sqrt{\pi} \rho g \sqrt{9 \cos ^{2} \psi-8}}\right]_{r_{1,2}},  \tag{2.21}\\
B_{3}=-\frac{2^{-1 / 43^{7 / 1}} x^{2} P}{\pi \rho g}, \quad B_{4}=-\frac{2 \sqrt{2} x^{2} P}{\sqrt{\pi} \rho g}
\end{gather*}
$$



Fig. 1.

Thus, the principal perturbations of the free surface are concentrated inside the angle $19^{\circ} 28^{\prime} \geqslant \Psi \geqslant-19^{\circ} 28^{\prime}$ on the left of the curve adc (Fig. 1) whose equation has the form $R=u_{1}(\psi) c t$. The free surface withthe region abco will be covered by stationary ship waves which represent the sum total of the longitudinal waves $\eta_{2}$ and the transverse waves $\eta_{1}$. Moreover, the equation of the curve abc has the form $R=c t u_{2}(\psi)$.

The free surface within the region abcda will be covered only by the transverse waves $\eta_{1}$. The elevation of the fluid within the angle on the right of the curve adc is of the same order as the elevation outside of the angle. The values of $u_{1,2}(\psi)$ are given in the table.
3. We shall now investigate the problem of the decay of the stationary waves generated by the moving pressures under consideration after stcpping the action of the pressures. The expressions for the potential and the fluid elevation which we have obtained in the previous paragraph can be written as

$$
\begin{gather*}
\varphi=\varphi_{1}-\varphi_{2}, \quad \zeta=\zeta_{1}-\zeta_{2}, \quad \varphi_{1,2}=-\frac{c p_{0}}{\pi^{2} \rho g} \operatorname{Im} \int_{0}^{\infty} K_{1,2}(r) e^{z r} d r  \tag{3.1}\\
\zeta_{1}=\frac{p_{0}}{\pi^{2} \rho g} \lim _{z \rightarrow-0} \operatorname{Re} \int_{0}^{\infty} I_{1}(r) e^{z r} d r-\frac{p_{0} a(x, y)}{\rho g}, \quad \zeta_{2}=\frac{p_{0}}{\pi^{2} \rho g} \lim _{z \rightarrow-0} \operatorname{Re} \int_{0}^{\infty} I_{2}(r) e^{z r} d r \tag{3.2}
\end{gather*}
$$

where $I_{1,2}, K_{1,2}$ are given by formulas (2.7) and (2.10). The contour $L$ is chosen so that $\zeta_{2}$ and $\varphi_{2}$ tend to zero as $t \rightarrow \infty$; therefore, the stationary motion will be determined by the potential $\Phi_{1}$, and the fluid elevation in this case will be determined by formula (3.2). Taking the moment of stopping the action of the pressures as the initial time $(t=0)$, we have the following equations to determine the function $\phi(x, y, z, t)$, the potential of the decaying wave motion in a coordinate system moving with velocity $c$ in the negative direction of the $x$-axis:


$$
\begin{equation*}
\Delta \varphi=0 \quad z<0 \tag{3.3}
\end{equation*}
$$

$$
\varphi_{t t}+g \varphi_{z}+2 c \varphi_{x t}+c^{2} \varphi_{x x}=0, \quad z=0
$$

$$
\begin{equation*}
\varphi(x, y, z, 0)=\varphi_{1}(x, y, z, 0) \tag{3.4}
\end{equation*}
$$

$$
\varphi_{t}+c \varphi_{x}=\varphi_{1 t}+c \varphi_{1 x}+p_{0} \rho^{-1} a
$$

$$
\begin{equation*}
t=0, \quad z=0 \tag{3.5}
\end{equation*}
$$

Since the function $\varphi_{1}-\varphi_{2}$ satisfies the initial conditions (1.3), it is then obvious that

Fig. 2.

$$
\varphi(x, y, z, t)=\varphi_{2}(x, y, z, t)
$$

will satisfy all the conditions (3.3) to (3.5) therefore, the fluid
elevation in the decaying motion will have the form $\zeta=\zeta_{2}$, where $\zeta_{2}$ is given by formula (3.2). Using the results of the investigation of the integral $I_{2}$ given by formula (2.11), we find the following final expression for the fluid elevation in the decaying motion for large $k R$ in a coordinate system moving with the velocity $c$

$$
\begin{aligned}
& \zeta= \begin{cases}\eta_{1}+\eta_{2} & \left(0<\psi<19^{\circ} 28^{\prime}\right) \\
O\left(x^{-1} R^{-1}\right) & \left(19^{\circ} 28^{\prime}<\psi \leqslant \pi\right)\end{cases} \\
& \eta_{1,2}= \begin{cases}B_{1,2}(x R)^{-1 / 2} \sin \left[N\left(r_{1,2}\right) \mp 1 / 4 \pi\right] & \left(R>c t u_{1,2}(\psi)\right) \\
0\left(x^{-1} R^{-1}\right) & \left(R<c t u_{1,2}(\psi)\right)\end{cases} \\
& \zeta= \begin{cases}B_{3}(x R)^{-1 / 4} \sin (1 / 2 \sqrt{3} x R) & \left(R>1 / 2 \sqrt{2} c t, \quad \psi=19^{\circ} 28^{\prime}\right) \\
O\left[(x R)^{-1 / 3}\right] & \left(R<1 / 2 \sqrt{2} c, \quad \psi=19^{\circ} 28^{\prime}\right)\end{cases} \\
& \zeta= \begin{cases}B_{4}(x R)^{-1 / 2} \sin (x R+1 / \pi) & (R>c t, \quad \psi=0) \\
O\left(x^{-1} R^{-1}\right) & (R<c t, \quad \psi=0)\end{cases}
\end{aligned}
$$

Here $N(r), B_{k}, r_{k}$ and $u_{k}$ are given by formulas (2.16), (2.19) and (2.21).

The principal perturbations in the decaying motion will be contained inside of the angle $19^{\circ} 28^{\prime} \geqslant \Psi \geqslant-19^{\circ} 28^{\prime}$ to the right of the curve abc (Fig. 2). The region abcd will be covered only by longitudinal waves and the region to the right of the curve adc will be covered by the complete system of ship waves.

As $t \rightarrow \infty$ the amplitude of oscillations of the free surface in all regions of the fluid tends to zero like a quantity of order $\left(g c^{-1} t\right)^{-1}$.

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